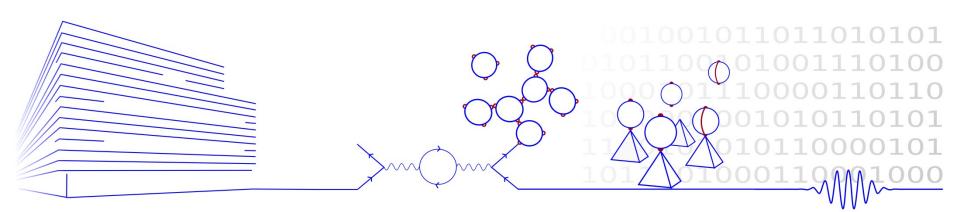


Potential Flow

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FMC - 2022/23



Overview

- Refs.: chap. 4 of Acheson, chap, 10 of Çengel, Faber.
- For irrotational flow, $\nabla \times \vec{V} = 0$, which implies that $\vec{V} = \pm \nabla \phi$.
- ϕ is a scalar field called the potential flow function.
- If the fluid is incompressible, then the continuity equation implies that $\nabla \cdot \vec{V} = 0$.
- In this case the potential flow function satisfies the Laplace equation $\nabla \cdot \vec{V} = \nabla \cdot \nabla \phi = \nabla^2 \phi = 0$
- We can obtain many velocity fields using the techniques used to solve Laplace's equation.

Velocity field

Given the flow potential, the velocity field is obtained from its gradient:

Cartesian coordinates,

$$u = \frac{\partial \phi}{\partial x}$$
 $v = \frac{\partial \phi}{\partial y}$ $w = \frac{\partial \phi}{\partial z}$

and in cylindrical coordinates,

$$u_r = \frac{\partial \phi}{\partial r}$$
 $u_{\theta} = \frac{1}{r} \frac{\partial \phi}{\partial \theta}$ $u_z = \frac{\partial \phi}{\partial z}$

Cartesian Coordinates (x, y, z)

$$\vec{V} = u\hat{i} + v\hat{j} + w\hat{k} = \frac{\partial\phi}{\partial x}\hat{i} + \frac{\partial\phi}{\partial y}\hat{j} + \frac{\partial\phi}{\partial z}\hat{k} = \nabla\phi$$
$$\nabla^2\phi = \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2} = 0$$

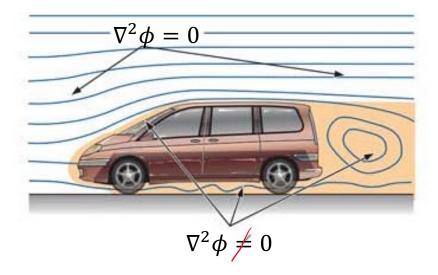
Cylindrical Coordinates (r, θ, z)

$$r^{2} = x^{2} + y^{2}, \ \theta = \tan^{-1} \left(\frac{y}{x} \right)$$
$$\vec{V} = u_{r}\hat{e}_{r} + u_{\theta}\hat{e}_{\theta} + u_{z}\hat{e}_{z} = \frac{\partial\phi}{\partial r}\hat{e}_{r} + \frac{1}{r}\frac{\partial\phi}{\partial\theta}\hat{e}_{\theta} + \frac{\partial\phi}{\partial z}\hat{e}_{z} = \nabla\phi$$
$$\nabla^{2}\phi = \frac{\partial^{2}\phi}{\frac{\partial r^{2}}{r} + \frac{1}{r}\frac{\partial\phi}{\partial r}} + \frac{1}{r^{2}}\frac{\partial^{2}\phi}{\partial\theta^{2}} + \frac{\partial^{2}\phi}{\partial z^{2}} = 0$$

Spherical Coordinates (r, θ , φ)

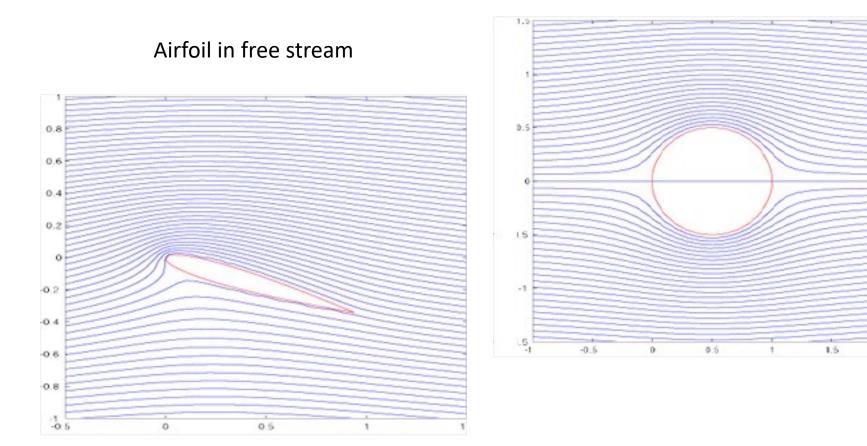
$$r^{2} = x^{2} + y^{2} + z^{2}, \ \theta = \cos^{-1}\left(\frac{x}{r}\right), \text{ or } x = r\cos\theta, \varphi = \tan^{-1}\left(\frac{z}{r}\right)$$
$$\vec{V} = u_{r}\hat{e}_{r} + u_{\theta}\hat{e}_{\theta} + u_{\varphi}\hat{e}_{\varphi} = \frac{\partial\phi}{\partial r}\hat{e}_{r} + \frac{1}{r}\frac{\partial\phi}{\partial\theta}\hat{e}_{\theta} + \frac{1}{r\sin\theta}\frac{\partial\phi}{\partial\varphi}\hat{e}_{\varphi} = \nabla\phi$$
$$\nabla^{2}\phi = \frac{\partial^{2}\phi}{\partial r^{2}} + \frac{2}{r}\frac{\partial\phi}{\partial r} + \frac{1}{r^{2}\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\phi}{\partial\theta}\right) + \frac{1}{r^{2}\sin^{2}\theta}\frac{\partial^{2}\phi}{\partial\varphi^{2}} = 0$$

Example (schematic)

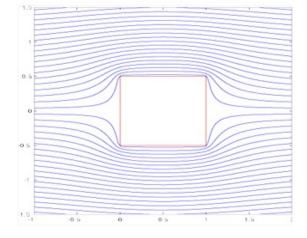


Examples (solutions of Laplace's equation)

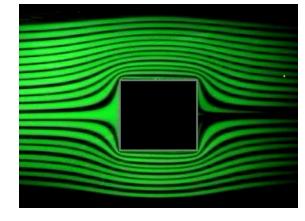
Cylinder in free stream



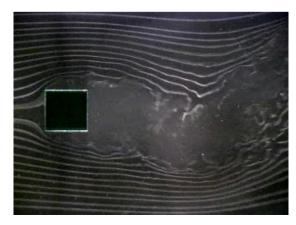
Examples

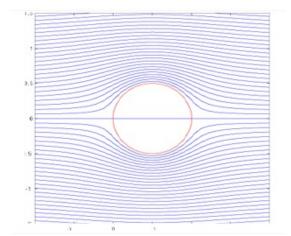


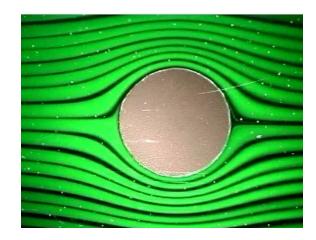


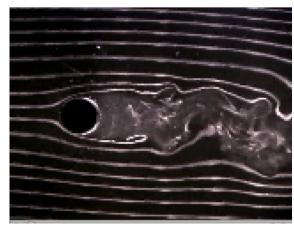


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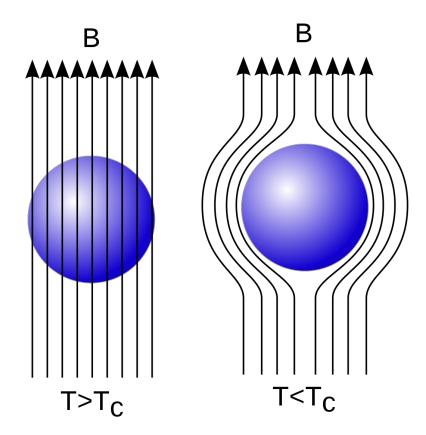








Superconductor



https://en.wikipedia.org/wiki/Meissner_effect

Ex.:

$$u = \alpha x, \quad v = -\alpha y, \quad w = 0$$

Back to Laplace's equation

For irrotational regions of flow:

$$\nabla^2 \phi = 0$$

In cartesian coordinates

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$$

In cylindrical coordinates

$$\nabla^2 \phi = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$$

Spherical and mixed coordinates may also be useful.

- The beauty of this is that we have combined three unknown velocity components (e.g., u, v, and w) into one unknown scalar field ϕ , eliminating two of the equations required for a solution.
- Once we obtain a solution, we can calculate all three components of the velocity field.
- The Laplace equation is well known since it shows up in several fields of physics, applied mathematics, and engineering. Various solution techniques, both analytical and numerical, are available in the literature.
- Solutions of the Laplace equation are dominated by the geometry (i.e., boundary conditions).
- The solution is valid for any incompressible fluid, regardless of its density or its viscosity, in regions of the flow in which the irrotational approximation is appropriate

Pressure

Of course we still need a dynamical equation to calculate the pressure field. This will be given by the Euler equation.

If gravity is the only body force, then

For irrotational regions of flow:

$$\rho \left[\frac{\partial \vec{V}}{\partial t} + (\vec{V} \cdot \vec{\nabla}) \vec{V} \right] = -\vec{\nabla} P + \rho \vec{g}$$

Or in its integrated form, the Bernoulli equation

Steady, incompressible flow:
$$\frac{P_1}{\rho} + \frac{V_1^2}{2} + gz_1 = \frac{P_2}{\rho} + \frac{V_2^2}{2} + gz_2$$

Since the flow is irrotational, we can apply Bernoulli to ANY two points in the flow domain.

Stream function

• For irrotational flows in 2D, the stream function obeys the Laplace equation:

 $\nabla^2 \psi = 0.$

- In potential 2D flow, both the flow potential and the stream function are solutions of the Laplace equation.
- Lines of constant flow potential are perpendicular to the streamlines (check).
- In axisymmetric flows the stream function obeys a linear equation but that is no longer Laplace's equation.

Stream function

For incompressible 2D flows:

$$u = \frac{\partial \psi}{\partial y}, \qquad v = -\frac{\partial \psi}{\partial x} \qquad \Longrightarrow \qquad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

Important property: ψ is constant along a streamline.

$$\frac{D \psi}{D t} = \frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla)\psi = u\frac{\partial \psi}{\partial x} + v\frac{\partial \psi}{\partial y} = \frac{\partial \psi}{\partial y}\frac{\partial \psi}{\partial x} - \frac{\partial \psi}{\partial x}\frac{\partial \psi}{\partial y} = 0 \implies \frac{D \psi}{D t} = 0$$

Generic coordinate system (only in 2D)

$$\mathbf{u} = \nabla \wedge (\psi \mathbf{k})$$

$$= \nabla \psi = (1 + e^{-2})$$

Complex potential

$$u = \frac{\partial \phi}{\partial x} = \frac{\partial \psi}{\partial y}, \qquad v = \frac{\partial \phi}{\partial y} = -\frac{\partial \psi}{\partial x}.$$

The complex potential is also a solution of the Laplace equation

$$w = \phi + i\psi$$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \qquad \qquad \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

Kelvin's circulation theorem

- An ideal fluid that is vorticity free at a given instant is vorticity free at all times.
- Demonstration: see Faber 120-122
- In three dimensions the conservation of vorticity (which corresponds to the conservation of angular momentum in mechanics) takes a somewhat subtle form.
- The circulation of a velocity field is defined to be

$$K\{t\} = \oint u\{x,t\} \cdot \mathrm{d} l,$$



where the line is a closed loop which moves with the fluid.

Circulation and vorticity

• By Stokes' theorem

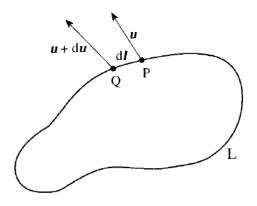
$$K = \oint_{C(t)} \mathbf{u} \cdot d\mathbf{l} = \int_{S(t)} (\underbrace{\mathbf{\nabla} \times \mathbf{u}}_{\Box}) \cdot \mathbf{n} dS = \int_{S(t)} \Omega \cdot \mathbf{n} dS,$$

where S(t) is a surface whose edges connect with C(t).

K is zero for all loops if Ω is zero in the domain!

Kelvin's theorem asserts that

$$\frac{DK}{Dt} = 0.$$



Demonstration

The loop moves with the flow and thus

$$\frac{DK}{Dt} = \oint \frac{D\vec{n}}{Dt} \cdot \vec{d\vec{r}} + \vec{n} \cdot \frac{D(\vec{d\vec{r}})}{Dt}$$

The second term is the relative velocity of two nearby points on the loop and can be written as $(\partial u/\partial l)dl$,

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$$\frac{D(d\vec{r})}{Dt} = d\vec{r} \cdot \nabla \vec{u}$$

Hence

$$\oint \vec{u} \cdot D(d\vec{\ell}) = \oint \vec{u} \cdot \left[(d\vec{\ell} \cdot \nabla) \cdot \vec{u} \right] = \frac{1}{2} \oint \nabla(\vec{u}^2) \cdot d\vec{\ell}$$

$$\int \int (\nabla \times \nabla \cdot \vec{u}^2) \cdot d\vec{S} = 0$$

$$= \int_{2}^{1} \int_{2}^{1} (\nabla \times \nabla \cdot \vec{u}^2) \cdot d\vec{S} = 0$$

$$= 0$$

$$= 0$$

$$= 0$$

If the fluid is incompressible, using Euler:

$$\frac{Du}{Dt} = -\nabla \left(\frac{p}{\rho} + gz\right),$$

$$\int_{C} \frac{Du}{Dt} \cdot d\tau = -\oint_{C} \nabla \left(\frac{p}{\rho} + gz\right) \cdot d\tau$$

$$\int_{C} \frac{Stokes}{2} - \int_{C} \left[\nabla \times \nabla \left(\frac{p}{\rho} + gz\right)\right] \cdot ds = 0$$

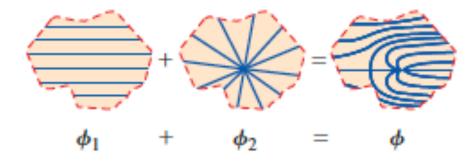
Therefore:

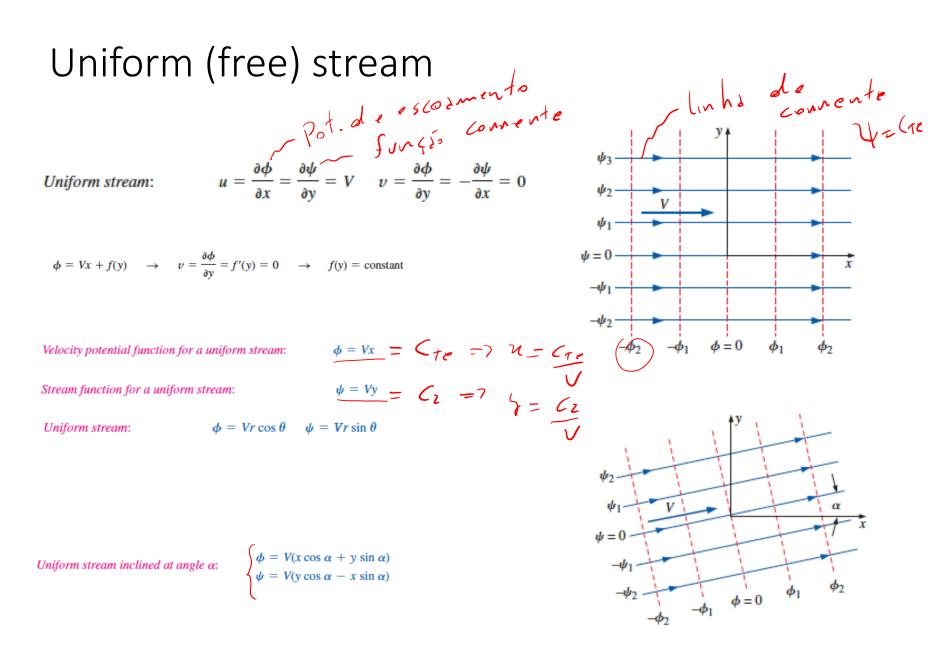
$$\frac{DK}{Dt} = 0 \qquad - \int (v do i de) (1 - v do i de) (1 - v do i de) (1 - v do de) (1 - v$$

Superposition

 $\vec{V} = \nabla \phi$

- Since the Laplace equation is a linear homogeneous differential equation, the linear combination of two or more solutions of the equation must also be a solution.
- For example, if ϕ_1 and ϕ_2 are each solutions of the Laplace equation, then $A \phi_1 + B \phi_2$ are also solutions, where A and B are arbitrary constants. $\nabla^2 \phi_r = \nabla^2 (A \phi_1 + B \phi_2) = A \nabla^2 \phi_1 + B \nabla^2 \phi_2$ • By extension, you may combine several solutions of the Laplace
- equation, and the combination is guaranteed to also be a solution.





Line source or sink

Let the volume flow rate per unit depth, be the line source strength, m

$$\frac{\dot{V}}{L} = 2\pi r u_r \qquad u_r = \frac{\dot{V}/L}{2\pi r}$$

The components of the velocity are

Line source:

$$u_r = \frac{\partial \phi}{\partial r} = \frac{1}{r} \frac{\partial \psi}{\partial \theta} = \frac{\dot{V}/L}{2\pi r} \qquad u_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta} = -\frac{\partial \psi}{\partial r} = 0$$

$$\frac{\partial \psi}{\partial r} = -u_{\theta} = 0 \quad \rightarrow \quad \psi = f(\theta) \quad \rightarrow \quad \frac{\partial \psi}{\partial \theta} = f'(\theta) = ru_r = \frac{\dot{V}/L}{2\pi}$$

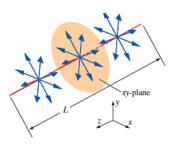
With solution

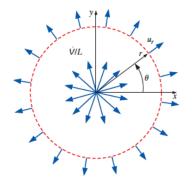
$$f(\theta) = \frac{\dot{V}/L}{2\pi}\theta + \text{constant}$$

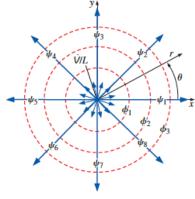
Line source at the origin:

+ constant

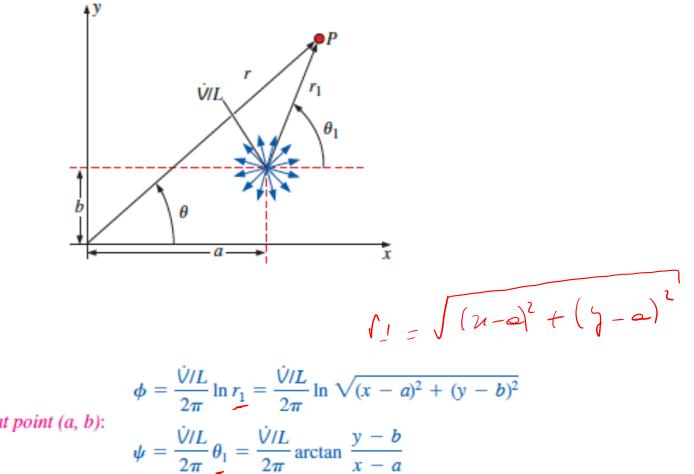
$$\phi = \frac{\dot{V}/L}{2\pi} \ln r \quad \text{and} \quad \psi = \frac{\dot{V}/L}{2\pi} \theta$$







Line source or sink at an arbitrary point



Line source at point (a, b):

Superposition of a source and sink of equal strength

Line source at (-a, 0): $\psi_1 = \frac{\dot{V}/L}{2\pi} \theta_1$ where $\theta_1 = \arctan \frac{y}{x+a}$ Similarly for the sink, Line sink at (a, 0): $\psi_2 = \frac{-\dot{V}/L}{2\pi} \theta_2$ where $\theta_2 = \arctan \frac{y}{x-a}$ Composite stream function: $\psi = \psi_1 + \psi_2 = \frac{\dot{V}/L}{2\pi} (\theta_1 - \theta_2)$ Final result, Cartesian coordinates: $\psi = \frac{-\dot{V}/L}{2\pi} \arctan \frac{2ay}{2\pi} = \frac{2ay}{2\pi}$

ult, Cartesian coordinates:
$$\psi = \frac{1}{2\pi} \arctan \frac{1}{x^2 + y^2 - a^2}$$

Final result, cylindrical coordinates:
$$\psi = \frac{-\dot{V}/L}{2\pi} \arctan \frac{2ar \sin \theta}{r^2 - a^2}$$

Using

$$\arctan(u) \pm \arctan(v) = \arctan\left(rac{u\pm v}{1\mp uv}
ight) \pmod{\pi}, \quad uv
eq 1\,.$$

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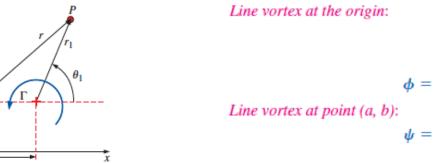
Line vortex

The radial component of the velocity is zero and

Line vortex:
$$u_r = \frac{\partial \phi}{\partial r} = \frac{1}{r} \frac{\partial \psi}{\partial \theta} = 0$$
 $u_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta} = -\frac{\partial \psi}{\partial r} = \frac{\Gamma}{2\pi r}$

where $\Gamma = 2\pi r u_{\theta}$, is the circulation, around a loop of radius r.



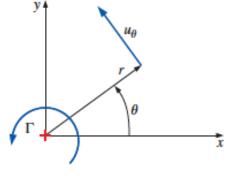


$$\phi = \frac{\Gamma}{2\pi} \theta \quad \psi = -\frac{\Gamma}{2\pi} \ln r$$

$$\phi = \frac{\Gamma}{2\pi} \theta_1 = \frac{\Gamma}{2\pi} \arctan \frac{y-b}{x-a}$$

prtex at point (a, b):

$$\psi = -\frac{\Gamma}{2\pi} \ln r_1 = -\frac{\Gamma}{2\pi} \ln \sqrt{(x-a)^2 + (y-b)^2}$$



y i

Superposition of a line sink and a line vortex at the origin

The stream function is

Superposition:

with streamlines

Streamlines:

 $\psi = \frac{\dot{V}/L}{2\pi}\theta - \frac{\Gamma}{2\pi}\ln r$ y, m 0.3 $r = \exp\left(\frac{(\dot{V}/L)\theta - 2\pi\psi}{\Gamma}\right)$ 0 x, m

Velocity components:

 $u_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta} = \frac{\dot{V}/L}{2\pi r}$ $u_{\theta} = -\frac{\partial \psi}{\partial r} = \frac{\Gamma}{2\pi r}$

Note that velocity diverges at the origin, which is a singularity (unphysical).

0.8

0.9

2

0.6

0.5

Sources and sinks

(Faber 4.4)

 $\overline{M} = U \hat{n}$

- The 1/R potential $\phi = -\frac{Q}{4\pi R}$ is a solution of Laplace's equation in $\mathcal{M}_{R=}$
- It describes isotropic flow with velocity $Q/4\pi R^2$
- If Q > 0 it is a source and it is a sink otherwise. Q is the discharge rate.
- Free stream potential $\phi = Ux_1$.
- Superposition of the two gives

$$u_{1} = U + \frac{Q}{4\pi R^{2}} \cos \theta, \quad (u_{2}^{2} + u_{3}^{2})^{1/2} = \frac{Q}{4\pi R^{2}} \sin \theta,$$

Sources and sinks

• Or in spherical coordinates,

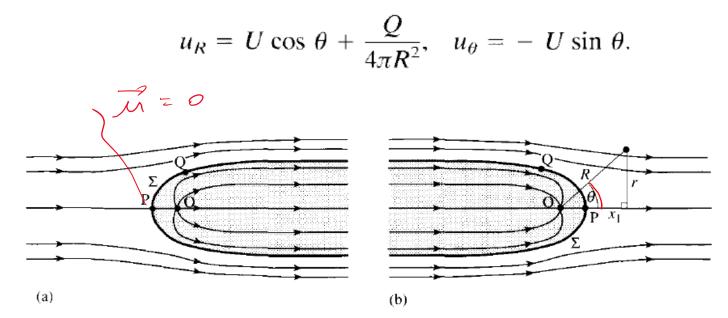
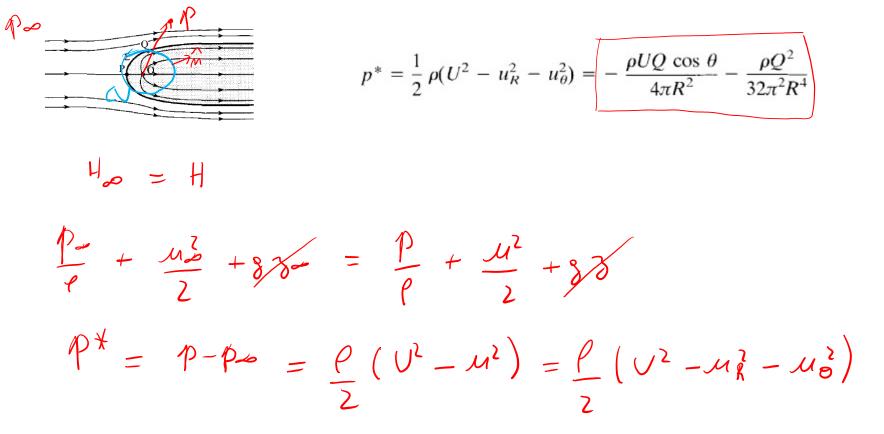


Figure 4.2 Lines of flow past (a) a point source, (b) a point sink. The surface of revolution Σ encloses all the fluid coming from, or destined for, the source or sink respectively.

Excess pressure and force

The excess pressure vanishes at infinity where the velocity is that of the free stream. Then Bernoulli gives for the dynamical pressure:



Total force in the direction x, exerted by this excess of pressure on the fluid inside a spherical control surface centered on O, of an arbitrary R.

$$F_{\pi} = \frac{1}{2} \rho U Q \int_{0}^{\pi} \left(\cos^{2} \theta \sin \theta + \frac{Q \cos \theta \sin \theta}{8\pi R^{2} U} \right) d\theta = \frac{1}{3} \rho U Q$$

$$F_{j} = \nabla_{j} \int_{0}^{\pi} \int_{0}^{\pi} dA \qquad j \qquad P = F \qquad dF = P dA$$

$$F_{\pi} = \int_{0}^{\pi} P^{\pi} dA \qquad cos \theta$$

$$= \int_{0}^{\pi} P^{\pi} cos \theta R^{2} rm d\theta \qquad dA = R d\theta \cdot R rm \theta$$

$$= R^{2} rm d\theta \qquad R^{an\theta} dA = R^{an\theta} A = R^{an\theta}$$

Rφ

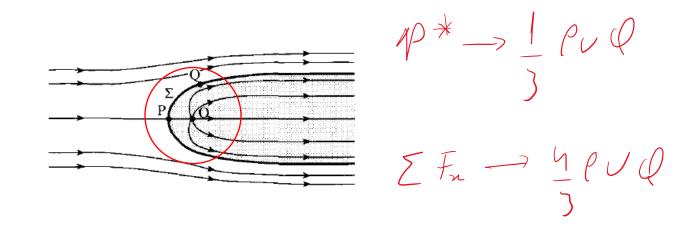
Rate of change of momentum

• The total force is equal to the rate of change of momentum in the x direction of the fluid, within the sphere:

$$\sum F_{\mathbf{x}} = \int_{0}^{\pi} \frac{\rho u_{1} u_{R} 2\pi R^{2} \sin \theta \, \mathrm{d}\theta}{V_{1} \omega_{R} 2\pi R^{2} \sin \theta \, \mathrm{d}\theta} = \int_{0}^{\pi} \left\{ U^{2} \cos \theta + \frac{UQ(1 + \cos^{2} \theta)}{4\pi R^{2}} + \frac{Q^{2} \cos \theta}{16\pi^{2} R^{4}} \right\} 2\pi R^{2} \sin \theta \, \mathrm{d}\theta$$
$$= \frac{4}{3} \rho UQ,$$

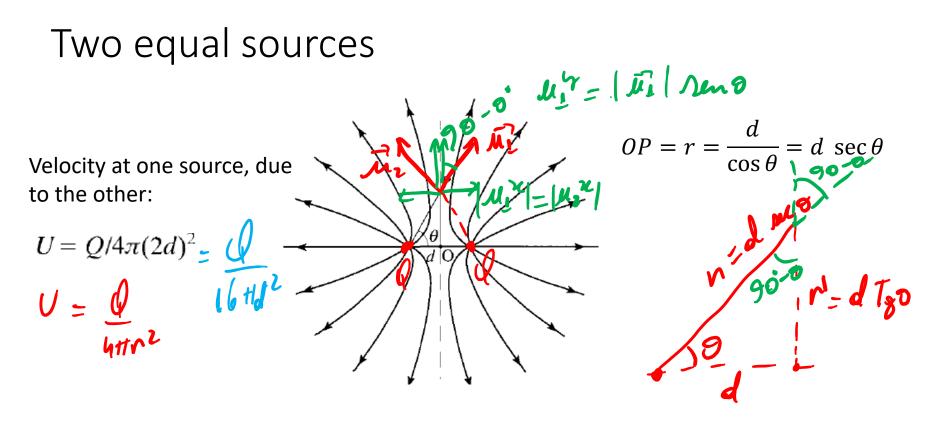
Reynolds transport theorem: $\frac{dB_{sys}}{dt} = \frac{d}{dt} \int_{CV} \rho b \, dV + \int_{CS} \rho b \vec{V}_r \cdot \vec{n} \, dA \qquad \vec{B} = b \, . \, m$ $\sum \vec{F} = \frac{d}{dt} \int_{CV} \rho \vec{V} \, dV + \int_{CS} \rho \vec{V} (\vec{V} \cdot \vec{n}) \, dA$

Rate of change of momentum



- There is then an additional force on the fluid in the x direction of magnitude ρUQ
- This has to be exerted by the source (sink) and thus the source (sink) will experience a reaction force

$$F = -\rho UQ.$$



On the plane bissecting the line joining the two sources the normal component of the velocity vanishes. The radial component (in the direction of OP), add and are given by:

 $\mathcal{U}_{p} = 2 \operatorname{Sun 9} \cdot \frac{Q}{4\pi (d \operatorname{Suc 9})^{2}} = \frac{2Q \sin \theta}{4\pi (d \sec \theta)^{2}}.$

 $T_{q\theta} = r' \rightarrow r'$

$$\int \frac{d}{dt} = \frac{d}{dt} = \frac{d}{dt} + \frac{d}{dt} = \frac{d}{dt} + \frac{d}{dt} + \frac{d}{dt} = \frac{d}{dt} + \frac{d}{dt} + \frac{d}{dt} + \frac{d}{dt} = \frac{d}{dt} + \frac{d}{dt$$

Excess pressure and force $p(y'_{n-1}, y'_{n-2}) = -\frac{p}{2}u^{2}$ $H_{ob} = H_{p} \Rightarrow p^{2} = \frac{p}{2}(y'_{n-1}, y'_{n-2}) = -\frac{p}{2}u^{2}$

• Assuming that the excess pressure vanishes at infinity, where **u** also vanishes, the excess pressure at P is (Bernoulli),

$$p^*\{\theta\} = -\frac{\rho Q^2 \sin^2 \theta \cos^4 \theta}{8\pi^2 d^4}.$$

• The fluid to the left of the bissecting plane experiences a force due to this excess pressure, given by

$$F_{n} = -\int_{0}^{\infty} p^{*}\{\theta\} 2\pi d \tan \theta \, d(d \tan \theta) = \frac{\rho Q^{2}}{4\pi d^{2}} \int_{0}^{\pi/2} \sin^{3} \theta \cos \theta \, d\theta = \frac{\rho Q^{2}}{16\pi d^{2}}$$

$$\int_{0}^{\pi} e^{i\theta} dF_{n} = \nabla_{ij} n_{j} dA \quad i \quad \text{Evlow} = \rho UQ.$$

$$\nabla_{ij} = -PS_{ij} = \rho UQ.$$

$$\int_{0}^{\pi} e^{i\theta} dF_{n} = (-P m_{n} dA)$$

$$Z \text{ problemas} \quad \text{prosec.}$$

Analytical solutions of Laplace's equation

(i) Two-dimensional circular polar coordinates (r, θ)

In this system Laplace's equation becomes

$$-) r \frac{\partial}{\partial r} \left\{ r \frac{\partial \phi}{\partial r} \right\} + \frac{\partial^2 \phi}{\partial \theta^2} = 0. r^2 x \frac{1}{\sqrt{2}} \frac{\partial}{\partial v} \left(v \frac{\partial \phi}{\partial v} \right) + \frac{1}{\sqrt{2}} \frac{\partial^2 \phi}{\partial \theta^2} = 0.$$

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Single-valued solutions in which the variables are separated can readily be found. They are:

$$\phi = \text{constant},$$

$$\phi \propto \phi_0 = \ln r, \qquad (4.22)$$

$$\phi \propto \phi_n = \frac{r^n \cos(n\theta)}{(n = \pm 1, \pm 2, \pm 3 \text{ etc.}]}. \qquad (4.23)$$

$$[n = \pm 1, \pm 2, \pm 3 \text{ etc.}].$$

$$(Fers) :$$

Ex.:

$$\phi_{n} = r^{n} \cos(n\theta).$$

$$r \frac{\partial}{\partial r} \left\{ r \frac{\partial \phi}{\partial r} \right\} + \frac{\partial^{2} \phi}{\partial \theta^{2}} = 0$$

$$f \cdot r^{n} \cdot \frac{\partial}{\partial r} = W \cap r^{n-2} \cdot \frac{\partial}{\partial r} \cdot \frac{\partial$$

$$2^{\circ} t_{ermo}: \frac{\partial \phi}{\partial \sigma} = -n^{m} \cdot n \cdot sin(\delta m)$$

$$1^{\circ} t \cdot + 2^{\circ} t \cdot = 0$$

$$\frac{\partial \phi}{\partial \sigma^{2}} = -n^{2} r^{m} \cos(n\sigma)$$

(iv) Three-dimensional spherical polar coordinates (R, θ, ϕ)

Laplace's equation in spherical polars has separated solutions which form a complete set, like the two-dimensional solutions described by (4.22) and (4.23). We need not list them fully here, because we shall be concerned only with problems in which the flow is axially symmetric, i.e. in which the flow potential does not vary with the azimuthal angle ϕ .² In these circumstances Laplace's equation simplifies to

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$$\longrightarrow$$
 $\frac{\partial}{\partial R}\left(R^2\frac{\partial\phi}{\partial R}\right) + \frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\phi}{\partial\theta}\right) = 0,$

and its separated solutions may be written as

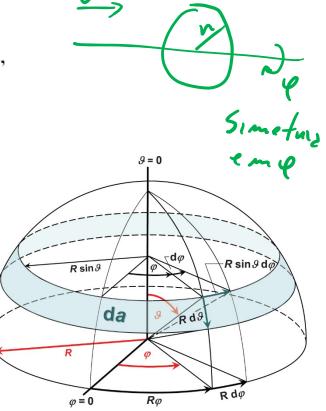
$$\phi \propto \phi_n^+ = R^n \mathbf{P}_n \{\cos \theta\},$$

$$\phi \propto \phi_n^- = R^{-(n+1)} \mathbf{P}_n \{\cos \theta\},$$

$$[n = 0, +1, +2, +3 \text{ etc.}].$$

$$\phi = \sum_n \phi_n^+ \cdot A_n^+ + \phi_n^- B_n^-$$

Laplacian in spherical coordinates



The Legendre functions $P_n\{\cos \theta\}$ may be expanded as polynomials in their argument, and we shall need the following expressions in particular:

$$/ P_0 \{ \cos \theta \} = 1,$$
 (4.29)

$$P_1\{\cos\theta\} = \cos\theta, \tag{4.30}$$

$$P_{2}\{\cos \theta\} = \frac{1}{2} (3 \cos^{2} \theta - 1).$$
 (4.31)

The full functions ϕ_n^+ and ϕ_n^- are properly called *zonal solid harmonics*. They are orthogonal to one another, and all other solutions of Laplace's equation in three dimensions which share their symmetry (or asymmetry) may be expressed as linear combinations of them [cf. (4.24)].

Some of the solutions described by (4.27) and (4.28) are of course trivial. Thus $\phi_0^+ = 1$ for all values of R and θ . As for $\phi_1^+ = R \cos \theta = x_1$ $\vec{x} = \sqrt{\hat{x}} = \sqrt{\hat{\phi}} = \sqrt{\hat{x}}$

$$\phi_1^+ = \frac{R \cos \theta}{\chi} = x_1 \qquad \qquad \vec{\mu} = \vec{V} \hat{\chi} = \vec{V} = \vec{V} \hat{\chi}$$

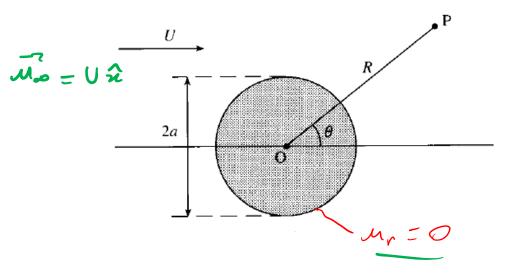
$$\phi_0^- = R^{-1}, \qquad \qquad Fonte = 3D$$

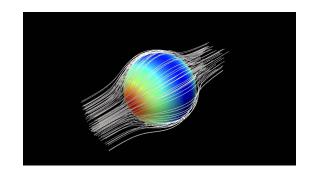
$$\vec{\mu} = \vec{U} \hat{\chi} = 3D$$

and

Potential flow around a sphere







$$\nabla^{2}\phi = \mathcal{O} = \mathcal{O} = \mathcal{O} \left(n^{2}\frac{\partial\phi}{\partial r}\right) + \frac{1}{ren}\frac{\partial}{\partial\theta}\left(ren \partial \frac{\partial\phi}{\partial\theta}\right) = \mathcal{O}$$

Solutions of the Laplace equation

where Po -

$$P_2 = Cono$$

General solution

$$\phi = \sum_{m} \left(A_{m}^{+} \phi_{m}^{+} + A_{m}^{-} \phi_{m}^{-} \right)$$

Boundary condition

$$A_{\pm}^{\dagger} = V$$

$$A_{\pm}^{\dagger} = 0$$

$$\frac{2}{2}v = 0, \quad M_{r} = 0 \Rightarrow \frac{2\phi}{2r}\bigg|_{r=0} = 0$$

$$\frac{2\phi_{m}}{2r} = -(m+1)v^{-(m+2)}P_{m}(\cos\theta)$$

$$\frac{2\phi_{m}}{2r} = -(m+1)v^{-(m+2)}P_{m}(\cos\theta)$$

Since the solution for a given set of boundary conditions is unique, only n=1 is needed.

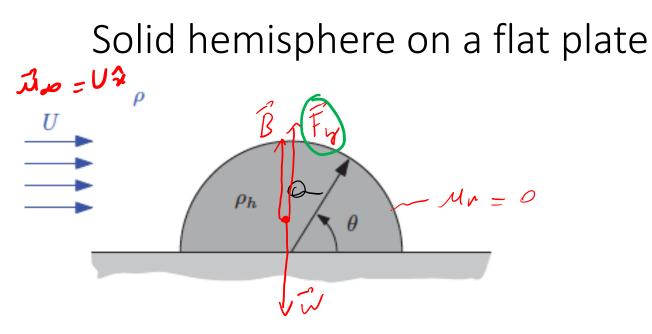
$$\begin{aligned}
\varphi_{\overline{i}} &= A_{\overline{i}} \quad v^{-2} & \text{cool} \\
\text{Fhus} & \sum_{\substack{z \in A_{i} \neq q_{i} \neq \\ \varphi = & \forall v \quad (cool) \neq A_{\overline{i}} \quad (cool) \neq A_{\overline{i}} \quad (cool) \neq A_{\overline{i}} \quad (v \neq A_{\overline{i}} \quad v^{2}) \\
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& \varphi_{\overline{$$

$$\Rightarrow \phi = c \Rightarrow \theta \left[Ur + \frac{V_{a}}{2r^{2}} \right]$$

Velocity

$$M_r = \frac{\partial \phi}{\partial r} = coo \left[U - \frac{U - 3}{r^3} \right]$$

$$M_0 = \frac{1}{r} \frac{2\phi}{2\phi} = -nem \Theta \left[U + \frac{U_0^3}{2r^3} \right]$$



 $F_{1} \xrightarrow{p_{2}} V_{2}$ $F_{2} \xrightarrow{p_{2}} V_{2}$

Due to high speed flow at the top of the sphere, we expect a low pressure at the top of the sphere. This pressure results in a lift force on the hemsiphere.

Potential

$$\nabla^2 \phi = \mathcal{O} = \mathcal{O} = \mathcal{O} \left(n^2 \frac{\partial \phi}{\partial r} \right) + \frac{1}{r m \partial \partial \partial} \left(r m \partial \frac{\partial \phi}{\partial \phi} \right) = \mathcal{O}$$

Same solution and boundary conditions as for a sphere in the previous slides.

Pressure in r=a

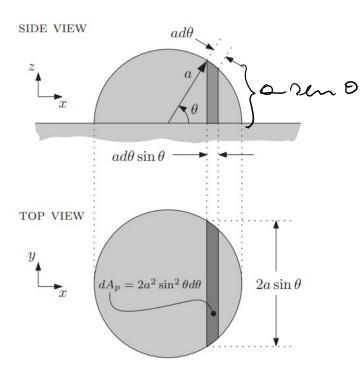
$$Mr = 0 , M_0 = -\frac{3}{2} \cup \Lambda_m 0$$

$$M_{\mu}^2 + M_0^2 \quad 2$$

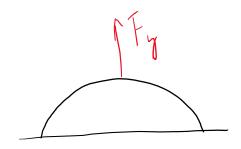
$$P^* = \frac{P}{2} \left(U^2 - M_{1(r=0)}^2 \right) = \frac{P}{2} \left[U^2 - \frac{9}{4} U^2 \Lambda_m^2 0 \right]$$
Lift force
$$\frac{1}{2} \vec{F}^2 = -p^* d\vec{A}$$

$$F_{\eta} = -\int p^* dA_{\eta}$$

$$V_{enifican} : F_{\pi} = 0$$



dAy = 202 ren 2000 = 20 mg. ado



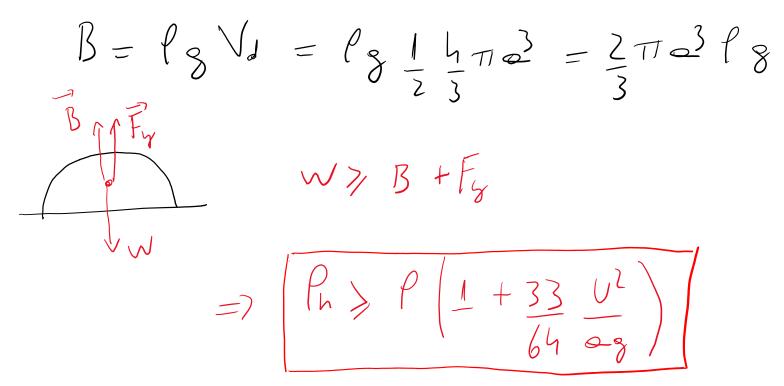
 $F_{y} = -\int \frac{f}{2} \frac{V}{2} \left(\frac{1-9}{4} rm^{2} \theta \right) 2 \sigma^{2} rm^{2} \theta d\theta$

 $= 11 P V^2 a^2 T$ 3)

Hemisphere weight

$$W = l_{h} \cdot \frac{1}{2} \cdot \frac{4}{3} \cdot \frac{1}{3} \cdot \frac{3}{3} = \frac{2}{3} \cdot \frac{1}{1} \cdot \frac{3}{2} \cdot \frac{3}{3} = \frac{2}{3} \cdot \frac{1}{1} \cdot \frac{3}{2} \cdot \frac{3}{3} \cdot \frac{$$

Buoyant force



Condition for the hemisphere to remain on the plate

Potential flow around a sphere and Magnus effect

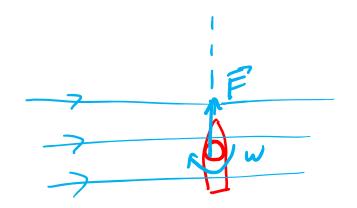
 $F = \sqrt{r} + \frac{r^2}{2} + \frac{r^2}{2} = C + e$ ТΡ



Rotor ship: propulsion by Magnus effect



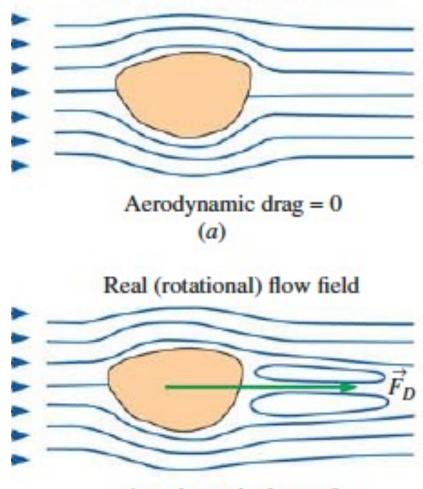
https://en.m.wikipedia.org/wiki/Rotor_ship





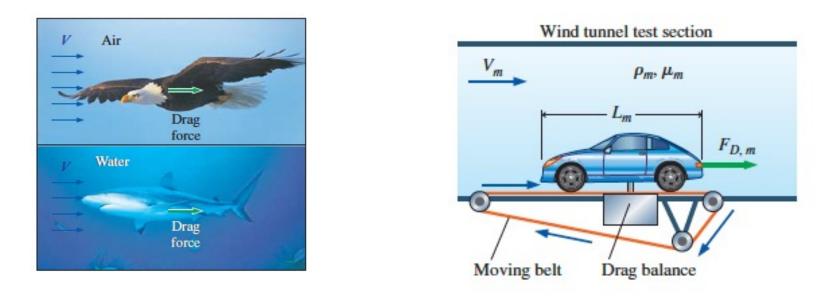
D'Alembert's paradox: In irrotational flow, the aerodynamic drag force on any body of any shape immersed in a uniform stream is zero.

"It seems to me that the theory (potential flow), developed in all possible rigor, gives, at least in several cases, a strictly vanishing resistance, a singular paradox which I leave to future Geometers [i.e. mathematicians - the two terms were used interchangeably at that time] to elucidate" Irrotational flow approximation



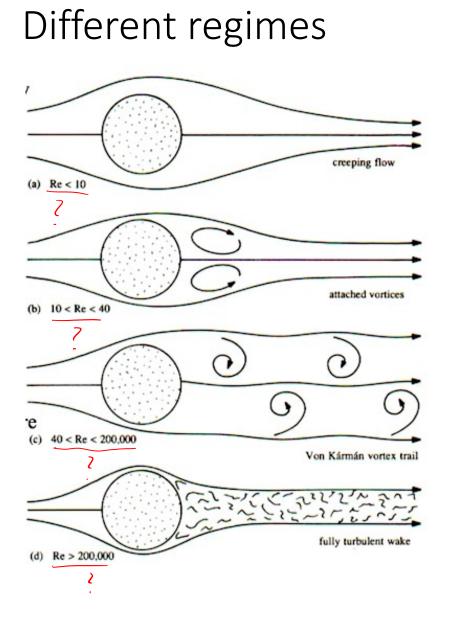
Aerodynamic drag $\neq 0$ (b)

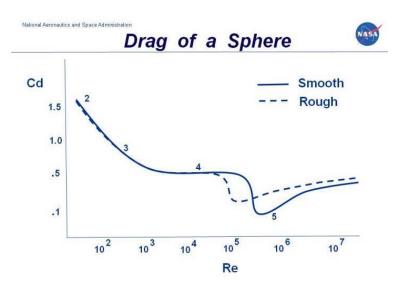
Drag force



In a real flow, the pressure on the back surface of the body is significantly less than that on the front surface, leading to a nonzero pressure drag on the body. In addition, the no-slip condition on the body surface leads to a nonzero viscous drag as well.

Thus, the irrotational flow falls short in its prediction of aerodynamic drag for two reasons: it predicts no pressure drag and it predicts no viscous drag.



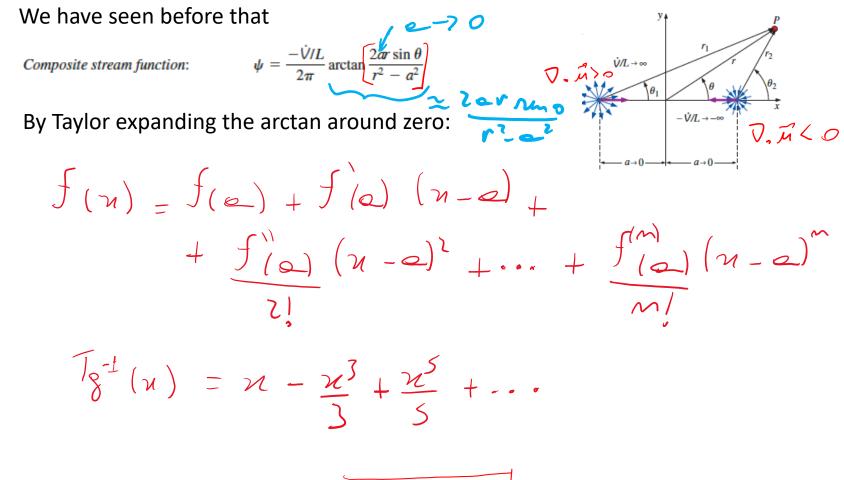


www.youtube.com/watch?v=fcjaxC-e8oY



Science of Golf: Why Golf Balls Have Dimples

Doublet: line source and sink close to origin



ollv

Stream function as $a \rightarrow 0$ *:*

 $\psi \rightarrow \frac{-a(V/L)r\sin\theta}{(2\pi)^2}$

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Doublet: line source and sink close to origin

Let a tend to zero at constant doublet strength K, to find

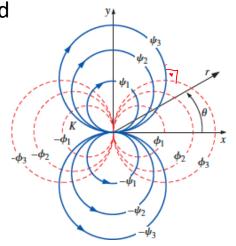
Doublet along the x-axis:

Doublet along the x-axis:

$$\psi = \frac{-a(\dot{V}/L)}{\pi} \frac{\sin\theta}{r} = \left[-K\frac{\sin\theta}{r}\right]$$
$$\phi = K\frac{\cos\theta}{r}$$

+ \$ = Ur cos s (Esc. uniforme)





Streamlines (solid) and equipotential lines (dashed) for a doublet of strength *K* located at the origin in the *xy*-plane and aligned with the *x*-axis.

Superposition of a uniform stream and a doublet: Flow over a circular cylinder

Superposition:

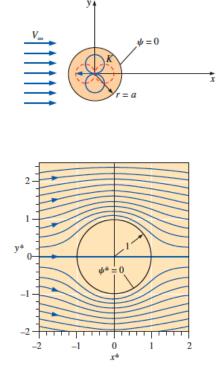
$$\psi = V_{\infty}r\sin\theta - K\frac{\sin\theta}{r}$$

For convenience we set $\psi = 0$ when r = aDoublet strength: $K = V_{\infty}a^2$

Alternate form of stream function:

$$\psi^* = \sin\theta \left(r^* - \frac{1}{r^*} \right)$$

$$\psi = V_{\infty} \sin \theta \left(r - \frac{a^2}{r} \right)$$



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Nondimensional streamlines:
$$r^* = \frac{\psi^* \pm \psi^*}{2}$$

$$* = \frac{\psi^* \pm \sqrt{(\psi^*)^2 + 4\sin^2\theta}}{2\sin\theta}$$